

Finite dim Hamiltonian formalism:

Phase space $M^n \cdot (u^1, \dots, u^n)$ $f_i = \frac{\partial F}{\partial u^i}, g_i = \frac{\partial G}{\partial u^i}$

Functions $f(u), g(u)$

Poisson bracket $\{f, g\} = f_i \omega^{ij} g_j$, ω^{ij} is a $(2,0)$ tensor

- skew-sym: $\{f, g\} = -\{g, f\}$ ($\Leftrightarrow \omega^{ij} = -\omega^{ji}$)

- Jacobi: $\{\{f, g\}, h\} + \{\{g, h\}, f\} + \{\{h, f\}, g\} = 0$

($\Leftrightarrow \omega^{ij}_{,k} \omega^{kl} + \omega^{jl}_{,k} \omega^{ki} + \omega^{li}_{,k} \omega^{kj} = 0$)

Darboux thm: If $\det(\omega^{ij}) \neq 0$, then ω^{ij} can be made constant coeff.

Hamiltonian system: $\dot{u}^i = \omega^{ij} h_j$, where h is the Hamiltonian

eg. $\omega^{ij} = \begin{pmatrix} 0 & I \\ -I & 0 \end{pmatrix} \Rightarrow$ Hamiltonian systems are $p_t^i = \frac{\partial h}{\partial q_i}$

$q_t^i = -\frac{\partial h}{\partial p_i}$

d-dim Hamiltonian formalism:

Phase space: $(u^i(x), \dots, u^n(x))$ on $M^n(u^1, \dots, u^n)$

Functionals: $F = \int f(x, u, u_x, \dots) dx$, $G = \int g(x, u, u_x, \dots) dx$

Poisson bracket: $\{F, G\} = \int \frac{\delta F}{\delta u^i} A^{ij} \frac{\delta G}{\delta u^j} dx$

Where $\frac{\delta F}{\delta u^i} = \frac{\partial f}{\partial u^i} - \left(\frac{\partial f}{\partial u^i_x} \right)_x + \left(\frac{\partial f}{\partial u^i_{xx}} \right)_{xx} - \dots$, etc.

& A^{ij} is a matrix differential operator in $\frac{d}{dx}$, with coeffs depending on u 's and their x -derivatives.

- Skew-sym + Jacobi identities (\Leftrightarrow complicated constraints for the coeffs of A^{ij}).

Darboux thm: If A^{ij} is "non-degenerate", then it can be transformed to u -independent form.

Hamiltonian systems:

$$u_t^i = A^{ij} \frac{\delta H}{\delta u^j}, \quad H = \int h(x, u, u_x, \dots) dx$$

eg $A^{ij} = \eta^{ij} \frac{d}{dx}, \quad \eta^T = \eta.$

\Rightarrow Ham. sys: $u_t^i = \eta^{ij} \left(\frac{\delta H}{\delta u^j} \right)_x.$

Shallow water eqns:

eg $\begin{cases} h_t + (uh)_x = 0 \\ u_t + uu_x + h_x = 0 \end{cases} \Leftrightarrow \begin{pmatrix} h \\ u \end{pmatrix}_t = \underbrace{- \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \frac{d}{dx}}_{A^{ij}} \begin{pmatrix} \frac{u^2}{2} + h \\ uh \end{pmatrix}$

$$H = \int \left(\frac{u^2 h}{2} + \frac{h^2}{2} \right) dx, \quad \frac{\delta H}{\delta u} = uh, \quad \frac{\delta H}{\delta h} = \frac{u^2}{2} + h$$

eg. (KdV)

$$u_t = 6uu_x - u_{xxx} = \underbrace{\frac{d}{dx}}_A \left(\frac{\delta H}{\delta u} \right), \quad H = \int \left(u^3 + \frac{u_x^2}{2} \right) dx$$

$$\frac{\delta H}{\delta u} = 3u^2 - u_{xx}$$

Dubrovin-Norikov

$$A^{ij} = g^{ij}(u) \frac{d}{dx} + b_{ik}^{ij}(u) u_x^k$$

Suppose $\det(g^{ij}) \neq 0$. Then set $b_{ik}^{ij} = -g^{is} \Gamma_{sk}^j$.

Thm: A^{ij} is Hamiltonian $\Leftrightarrow g^{ij}$ is flat metric & Γ_{sk}^j its Levi-Civita connection.

$$A^{ij} = g^{ij}(u) \frac{d}{dx} + b_{ik}^{ij}(u) u_x^k + c u_x^i \left(\frac{d}{dx}\right)^{-1} u_x^j$$

Note: $u_x^i \left(\frac{d}{dx}\right)^{-1} u_x^j h_j = u_x^i \left(\frac{d}{dx}\right)^{-1} h_x = u_x^i h$

Thm: A^{ij} Hamiltonian $\Leftrightarrow g^{ij}$ metric of constant curvature c .

$$A^{ij} = g^{ij}(u) \frac{d}{dx} + b_{ik}^{ij}(u) u_x^k + w_k^i(u) u_x^k \left(\frac{d}{dx}\right)^{-1} w_l^j(u) u_x^l$$

Thm: Skew-sym & Jacobi id.

$$\Leftrightarrow \begin{cases} g_{is} w_k^s = g_{ks} w_i^s \\ \nabla_k w_j^i = \nabla_j w_k^i \\ R_{kl}^{ij} = w_k^i w_l^j - w_l^i w_k^j \end{cases} \quad \begin{array}{l} \text{(Gauss-Peterson} \\ \text{-Codazzi eqns)} \end{array}$$

\mathbb{F}^{n+1}

$$\left. \begin{array}{c} \overbrace{g_{ij}(u), h_{ij}(u)} \\ \underbrace{\hspace{10em}} \end{array} \right\}$$

$$w_k^i = g^{is} h_{sk}$$

hypersurface $M^n(u^1, \dots, u^n)$

Dirac bracket: $\tilde{\omega}^{ij} = \omega^{ij} - \{u_i, f^\alpha\} \{f^\alpha, f^{\beta\gamma}\}^{-1} \{f_\beta, u_j\}$

$\square f_\alpha(u) = 0.$